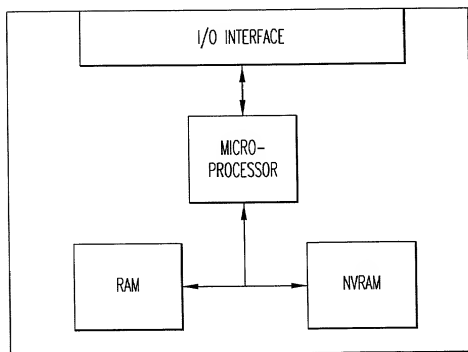
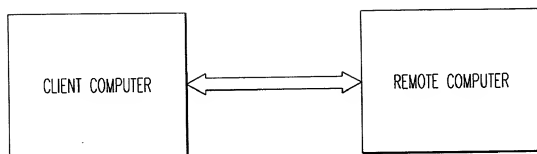


*FIG. 2*



*FIG. 3*



***FIG. 4***



FIG. 5A

FIG. 5C

INPUT \ STATE		0	1	2
STATE	0	(1,1)	(2,2)	(0,2)
	1	(1,1)	(1,2)	(0,0)
	2	(2,2)	(2,2)	(2,2)

FIG. 5B

INPUT \ STATE		0	1	2
STATE	0	(1,1)	(2,2)	(0,2)
	1	(1,1)	(1,2)	(0,0)
	2	(2,2)	—	(2,2)

FIG. 5D

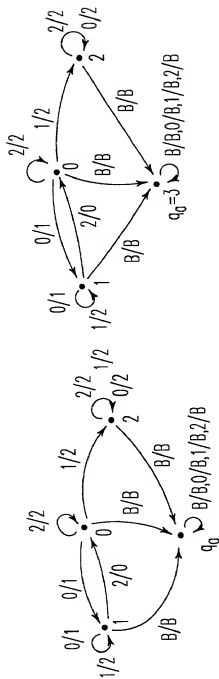


FIG. 6A

FIG. 6C

CORRESPONDING FUNCTION TABLE

INPUT STATE	0	1	2	B
0	(1,1)	(2,2)	(0,2)	( $q_0$ ,B)
1	(1,1)	(1,2)	(0,0)	( $q_0$ ,B)
2	(2,2)	(2,2)	(2,2)	( $q_0$ ,B)
$q_0$	( $q_0$ ,B)	( $q_0$ ,B)	( $q_0$ ,B)	( $q_0$ ,B)

FIG. 6B

CORRESPONDING FUNCTION TABLE

INPUT STATE	0	1	2	B
0	(1,1)	(2,2)	(0,2)	(3,B)
1	(1,1)	(1,2)	(0,0)	(3,B)
2	(2,2)	—	(2,2)	(3,B)
$q_0=3$	(3,B)	(3,B)	(3,B)	(3,B)

FIG. 6D

$$\left\{ \begin{array}{l}
 \text{INPUT SPACE: } \Sigma' = \{0, 1, 2, B\} \\
 \text{STATE SPACE: } Q' = \{0, 1, 2, q_0\}, \quad q_0 = 3 \\
 \text{OUTPUT SPACE: } \Delta' = \{0, 1, 2, 3\} \\
 \\
 \text{VECTORIZATION EXAMPLE FOR } N=2: \\
 \text{INPUT SPACE: } \Sigma' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(1,0)}, \overset{B}{(1,1)} \} \\
 \text{STATE SPACE: } Q' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(1,0)}, \overset{q_0=3}{(1,1)} \} \\
 \text{OUTPUT SPACE: } \Delta' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(1,0)}, \overset{3}{(1,1)} \}
 \end{array} \right.$$

**FIG. 7A**

$$\left\{ \begin{array}{l}
 \text{VECTORIZATION EXAMPLE FOR } N=3: \\
 \text{INPUT SPACE: } \Sigma' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(0,2)}, \overset{B}{(1,0)} \} \\
 \text{STATE SPACE: } Q' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(0,2)}, \overset{q_0=3}{(1,0)} \} \\
 \text{OUTPUT SPACE: } \Delta' = \{ \overset{0}{(0,0)}, \overset{1}{(0,1)}, \overset{2}{(0,2)}, \overset{B}{(1,0)} \}
 \end{array} \right.$$

**FIG. 7B**

$$\left\{ \begin{array}{l}
 \text{VECTORIZATION EXAMPLE FOR } N \geq 4 \\
 \text{INPUT SPACE: } \Sigma' = \{ \overset{0}{(0)}, \overset{1}{(1)}, \overset{2}{(2)}, \overset{B}{(3)} \} \\
 \text{STATE SPACE: } Q' = \{ \overset{0}{(0)}, \overset{1}{(1)}, \overset{2}{(2)}, \overset{q_0=3}{(3)} \} \\
 \text{OUTPUT SPACE: } \Delta' = \{ \overset{0}{(0)}, \overset{1}{(1)}, \overset{2}{(2)}, \overset{B}{(3)} \}
 \end{array} \right.$$

**FIG. 7C**

VECTORIZATION EXAMPLE FOR  $N'=2$ :

INPUT SPACE:  $\Sigma' = \{(0,0), (0,1), (1,0), (1,1)\}$

STATE SPACE:  $Q' = \{(0,0), (0,1), (1,0), (1,1)\}$

OUTPUT:  $\Delta' = \{(0,0), (0,1), (1,0), (1,1)\}$

IN THIS CASE  $N$  MAY BE SET TO ANY PRIME NUMBER  $\geq 2$ .

SELECTING PRIMES  $N > 2$  RESULTS IN  $(N-2)^2$  INPUT, STATE AND OUTPUT REPRESENTATIONS THAT INITIALLY REMAIN UNUSED.

**FIG. 8A**

VECTORIZATION EXAMPLE FOR  $N'=3$ :

INPUT SPACE:  $\Sigma' = \{(0,0), (0,1), (0,2), (1,0)\}$

STATE SPACE:  $Q' = \{(0,0), (0,1), (0,2), (1,0)\}$

OUTPUT:  $\Delta' = \{(0,0), (0,1), (0,2), (1,0)\}$

IN THIS CASE  $N$  MAY BE SET TO ANY PRIME NUMBER  $\geq 3$ .

FOR EVERY  $N$  THERE ARE  $N^2-4$  UNUSED REPRESENTATIONS FOR INPUT VECTORS (INPUT "SYMBOLS"), STATE VECTORS, AND OUTPUT VECTORS (OUTPUT "SYMBOLS").

**FIG. 8B**

VECTORIZATION EXAMPLE FOR  $N' \geq 4$ :

INPUT SPACE:  $\Sigma' = \{(0), (1), (2), (3)\}$

STATE SPACE:  $Q' = \{(0), (1), (2), (3)\}$

OUTPUT:  $\Delta' = \{(0), (1), (2), (3)\}$

IN THIS CASE  $N$  MAY BE SET TO ANY PRIME NUMBER  $\geq 5$

FOR EVERY  $N$  THERE ARE  $N-4$  UNUSED REPRESENTATIONS FOR INPUT VECTORS, STATE VECTORS, AND OUTPUT VECTORS.

SELECTING AN  $N$  SUCH THAT THERE ARE MORE VALUES FOR  $N$  THAN OUTPUT VECTORS, INPUT VECTORS OR STATES IS SOMETHING THAT CAN BE DONE TO INCREASE THE POSSIBILITIES FOR INTRODUCING RANDOMNESS INTO THE PLAINTEXT STATES MACHINE

**FIG. 8C**

STATE \ INPUT		(0,0)	(0,1)	(0,2)	(1,0)	
		(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))
q <sub>0</sub> =	0	(0,0)	((0,1),(0,1))	((0,2),(0,2))	((0,0),(0,2))	((1,0),(1,0))
	1	(0,1)	((0,1),(0,1))	((0,1),(0,2))	((0,0),(0,0))	((1,0),(1,0))
	2	(0,2)	((0,2),(0,2))	————	((0,2),(0,2))	((1,0),(1,0))
	3	(1,0)	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))	((1,0),(1,0))
	4	(1,1)	————	————	————	————
	5	(1,2)	————	————	————	————
	6	(2,0)	————	————	————	————
	7	(2,1)	————	————	————	————
	8	(2,2)	————	————	————	————

FIG. 9A



INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)	(1,1)	(1,2)	(2,0)	(2,1)	(2,2)
(0,0)	$((0,1)(0,1))$	$((0,2)(0,2))$	$((0,0)(0,2))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(0,1)	$((0,1)(0,1))$	$((0,1)(0,2))$	$((0,0)(0,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(0,2)	$((0,2)(0,2))$	$((1,0)(1,0))$	$((0,2)(0,2))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(1,0)	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(1,1)	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(1,2)	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(2,0)	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(2,1)	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$
(2,2)	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$	$((1,0)(1,0))$

FIG. 9B

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)	(1,1)	(1,2)	(2,0)	(2,1)	(2,2)
(0,0)	$((0,1),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((1,0),(1,0))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(0,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(0,2)	$((0,2),(0,2))$	$((*,*)_{\lambda}(*,*))$	$((0,2),(0,2))$	$((1,0),(1,0))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(1,0)	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(1,1)	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(1,2)	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(2,0)	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(2,1)	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$
(2,2)	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$	$((*,*)_{\lambda}(*,*))$

FIG. 10

INPUT STATE \	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((0,1),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((1,0),(1,0))$
(0,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	$((1,0),(1,0))$
(1,0)	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$
(1,1)				

*FIG. 11A*

INPUT STATE \	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((0,1),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((1,0),(1,0))$
(0,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	$((1,0),(1,0))$
(1,0)	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$
(1,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$

*FIG. 11B*

• (1,1)

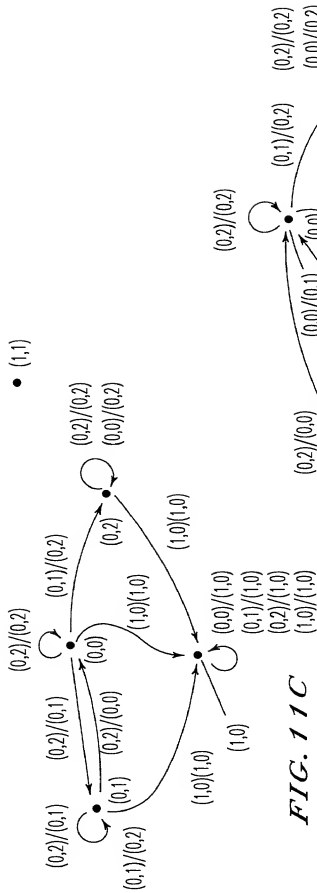


FIG. 11C

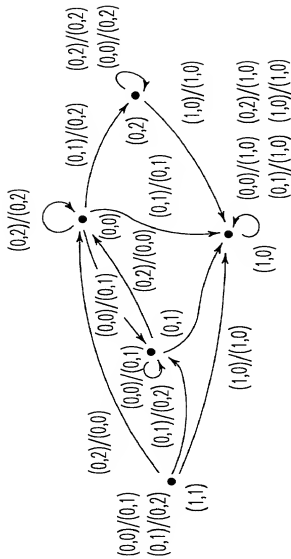


FIG. 11D

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((0,1),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((1,0),(1,0))$
(0,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	$((1,0),(1,0))$
(1,0)	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$
(1,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$

*FIG. 12A*

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((0,1),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((1,0),(1,0))$
(0,1)	$((0,1),(0,1))$	$((1,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	$((1,0),(1,0))$
(1,0)	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$
(1,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$

*FIG. 12B*

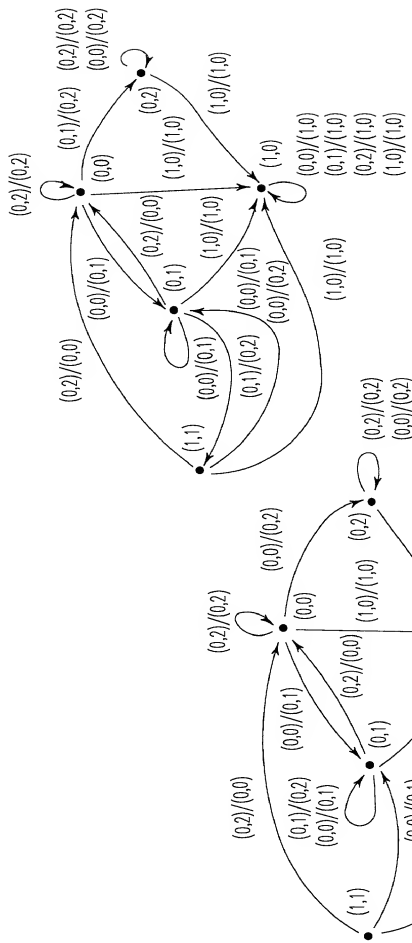


FIG. 12C

FIG. 12D

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((0,1),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((1,0),(1,0))$
(0,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	$((1,0),(1,0))$
(1,0)	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$	$((1,0),(1,0))$
(1,1)	$((0,1),(0,1))$	$((0,1),(0,2))$	$((0,0),(0,0))$	$((1,0),(1,0))$

*FIG. 13A*

INPUT STATE	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	<del><math>((1,0),(0,1))</math></del>	$((0,2),(0,2))$	$((0,0),(0,2))$	<del><math>((0,1),(1,0))</math></del>
(0,1)	<del><math>((0,1),(1,0))</math></del>	<del><math>((0,1),(1,0))</math></del>	<del><math>((0,1),(1,0))</math></del>	<del><math>((0,1),(1,0))</math></del>
(0,2)	$((0,2),(0,2))$	————	$((0,2),(0,2))$	<del><math>((0,1),(1,0))</math></del>
(1,0)	<del><math>((1,0),(0,1))</math></del>	<del><math>((1,0),(0,2))</math></del>	<del><math>((0,0),(0,0))</math></del>	<del><math>((0,1),(1,0))</math></del>
(1,1)	<del><math>((1,0),(0,1))</math></del>	<del><math>((1,0),(0,2))</math></del>	$((0,0),(0,0))$	<del><math>((0,1),(1,0))</math></del>

*FIG. 13B*

INPUT STATE \	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((1,0),(0,1))$	$((0,2),(0,2))$	$((0,0),(0,2))$	$((0,1),(1,0))$
(0,1)	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$
(0,2)	$((0,2),(0,2))$	—	$((0,2),(0,2))$	$((0,1),(1,0))$
(1,0)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,0),(0,0))$	$((0,1),(1,0))$
(1,1)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,0),(0,0))$	$((0,1),(1,0))$

*FIG. 14A*

INPUT STATE \	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((1,0),(0,1))$	$((0,2),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,2))$
(0,1)	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$
(0,2)	$((0,2),(0,2))$	—	$((0,1),(1,0))$	$((0,2),(0,2))$
(1,0)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,0))$
(1,1)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,0))$

*FIG. 14B*



INPUT STATE \	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((1,0),(0,1))$	$((0,2),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,2))$
(0,1)	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$	$((0,1),(1,0))$
(0,2)	$((0,2),(0,2))$	—	$((0,1),(1,0))$	$((0,2),(0,2))$
(1,0)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,0))$
(1,1)	$((1,0),(0,1))$	$((1,0),(0,2))$	$((0,1),(1,0))$	$((0,0),(0,0))$

*FIG. 15A*

INPUT STATE \	(0,0)	(0,1)	(0,2)	(1,0)
(0,0)	$((1,0),(0,1))$	$\{(0,2),(1,0)\}$	$\{(0,1),(0,2)\}$	$\{(0,0),(1,0)\}$
(0,1)	$\{(0,1),(0,2)\}$	$\{(0,1),(0,2)\}$	$\{(0,1),(0,2)\}$	$\{(0,1),(0,2)\}$
(0,2)	$\{(0,2),(1,0)\}$	—	$\{(0,1),(0,2)\}$	$\{(0,2),(1,0)\}$
(1,0)	$((1,0),(0,1))$	$((1,0),(1,0))$	$\{(0,1),(0,2)\}$	$((0,0),(0,0))$
(1,1)	$((1,0),(0,1))$	$((1,0),(1,0))$	$\{(0,1),(0,2)\}$	$((0,0),(0,0))$

*FIG. 15B*

STATE \ INPUT	INPUT	
	(0,0)	
(0,0)	$((0,1)(0,1))$	

FIG. 16A

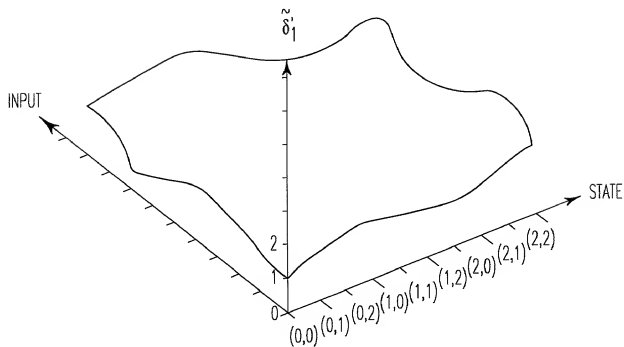


FIG. 16B

PRECALCULATE  $a_k(x)$  FOR  $k=\{0,1,2,4,5\} < Z_{11}$ .

PRECOMPUTATION RESULTS IN THE SERIES OF POLYNOMIALS

$$a_0(x)$$

$$a_1(x)$$

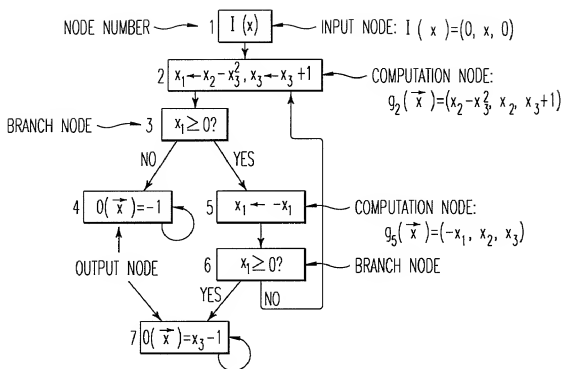
$$a_2(x)$$

$$a_4(x)$$

$$a_5(x)$$

REPRESENTED BY THEIR RESPECTIVE ARRAYS OF COEFFECIENTS

***FIG. 17***



- WHEN RESTRICTING A BSS MACHINE TO A FINITE FIELD  $\mathbb{Z}_N$  THE CHOICE OF  $N$  IS DICTATED BY THE FOLLOWING:
  - 1)  $N$  MUST BE A PRIME NUMBER
  - 2)  $N$  MUST BE AT LEAST AS GREAT AS THE NUMBER OF NODES
  - 3)  $N$  MUST MAKE ALLOWANCE FOR CONSTANTS USED IN THE MACHINE
  - 4)  $N$  MUST ACCOMMODATE USER REQUIREMENTS
- FOR THE ABOVE EXAMPLE:
  - $N$  SATISFIES THE FIRST CONDITION IF IT IS EQUAL TO 2, 3, 5, 7, 11,...
  - $N$  SATISFIES THE SECOND CONDITION IF IT IS  $\geq 7$
  - $N$  THE GREATEST CONSTANTS HAVE ABSOLUTE VALUE 1, SO  $N$  SATISFIES THE THIRD CONDITION IF IT IS  $\geq 2$
  - IF THE USER REQUIRES THAT THE  $x$  INPUT MUST BE ABLE TO BE AS LARGE AS 100,  $N$  SATISFIES THE FOURTH CONDITION IF IT IS  $> 100$ . THE LEAST  $N$  SATISFYING ALL FOUR CONDITIONS WOULD THEN BE  $N=101$
- SINCE ALL MAPPINGS IN THE BSS MACHINE ABOVE ARE POLYNOMIAL, THE RESTRICTION OF COMPUTATION MAPPINGS TO POLYNOMIAL MAPPINGS IS ALREADY SATISFIED.
- THE NEW NODE-NUMBERING CONVENTION SIMPLY SUBTRACTS 1 FROM EACH NODE NUMBER, SUCH THAT NUMBERING BEGINS AT 0.

1	2	3	4	5	6	7
↓	↓	↓	↓	↓	↓	↓
0	1	2	3	4	5	6

FIG. 18

THE FULL STATE SPACE OF THE BSS MACHINE, AS ADAPTED SO FAR, IS:

$\underbrace{\{0, \dots, 6\}}_{\text{NODE NUMBER SPACE}} \times \underbrace{\mathbb{Z}_N \times \mathbb{Z}_N \times \mathbb{Z}_N}_{\text{STATE SPACE}}$ 
 CORRESPONDING VECTORS HAVE THE COMPONENTS:
 

n	x <sub>1</sub>	x <sub>2</sub>	x <sub>3</sub>
---	----------------	----------------	----------------

THE REVISED FULL STATE SPACE ADDS THE OUTPUT AND INPUT COMPONENTS:

$\{0, \dots, 6\} \times \mathbb{Z}_N \times \mathbb{Z}_N \times \underbrace{\mathbb{Z}_N}_{\text{OUTPUT}} \times \underbrace{\mathbb{Z}_N}_{\text{INPUT}}$ 
 CORRESPONDING VECTORS HAVE THE COMPONENTS:
 

n	x <sub>1</sub>	x <sub>2</sub>	x <sub>3</sub>	x <sub>4</sub>	x <sub>5</sub>
---	----------------	----------------	----------------	----------------	----------------

  
OUTPUT
INPUT

ALSO A COMPUTATION MAPPING  $g_i$  IS ADDED TO EVERY NODE THAT DOESN'T ALREADY HAVE ONE. THUS FOR EACH NODE VIEWED IN ISOLATION:

- NODE 0:  $g_0(\vec{x}) = (0, x_5, 0, 0, x_5)$  IS ADDED  
 NODE 1: " $g_2$ " (NOW  $g_1$ ) IS CHANGED TO  $g_1(\vec{x}) = (x_2 - x_3^2, x_2, x_3 + 1, 0, x_5)$   
 NODE 2:  $g_2(\vec{x}) = (x_1, x_2, x_3, 0, x_5)$  IS ADDED  
 NODE 3:  $g_3(\vec{x}) = (x_1, x_2, x_3^{N-1}, x_5)$  IS ADDED  
 NODE 4:  $g_4$  (PREVIOUSLY " $g_5$ ") IS CHANGED TO  $g_4(\vec{x}) = (-x_1, x_2, x_3, 0, x_5)$   
 NODE 5:  $g_5(\vec{x}) = (x_1, x_2, x_3, 0, x_5)$  IS ADDED  
 NODE 6:  $g_6(\vec{x}) = (x_1, x_2, x_3, x_3 - 1, x_5)$  IS ADDED

AS THE RELATION  $\geq 0$  HOLDS FOR ALL ELEMENTS IN  $\mathbb{Z}_N$ , IT IS REPLACED BY A SERIES OF SET INCLUSION RELATIONS. BECAUSE  $\mathbb{Z}_N$  DOES NOT HAVE NEGATIVE NUMBERS AS ELEMENTS, THE RELATIONS WILL NOT HAVE AN EXACT CORRESPONDENCE TO THE ORIGINAL RELATIONS. REASONABLE SET INCLUSION RELATIONS FOR THIS EXAMPLE ARE:

FOR NODE 2:  $\in \mathbb{Z}_p - \{0\}$  WITH THE SAME MAPPING IN NODE 1 AS BEFORE.  
 FOR NODE 5:  $\in \{1\}$ , CHANGING  $g_4$  TO  $g_4(\vec{x}) = (x_3 + 1, x_2, x_3, 0, x_5)$

FIG. 19

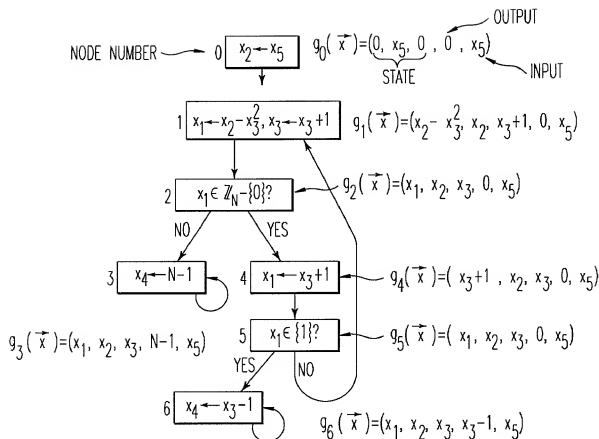


FIG. 20A

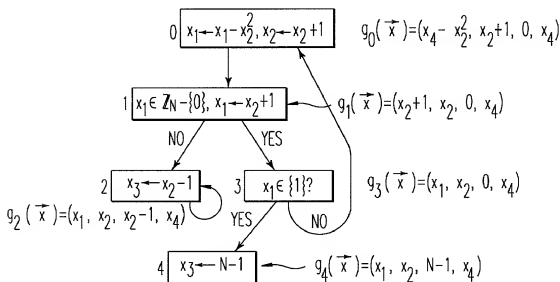


FIG. 20B

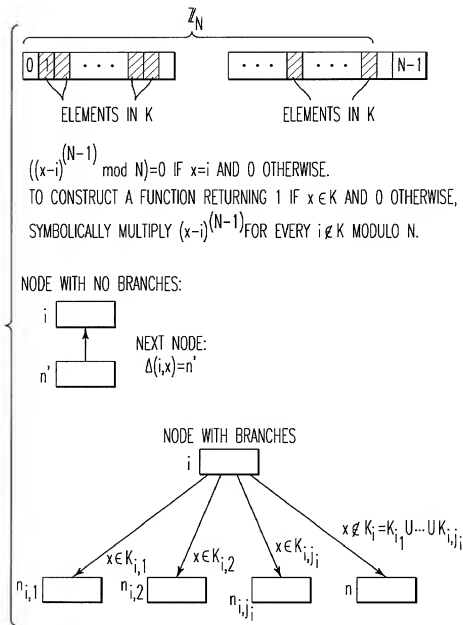


FIG. 21

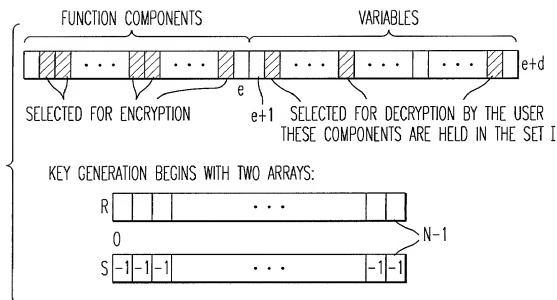


FIG. 22A

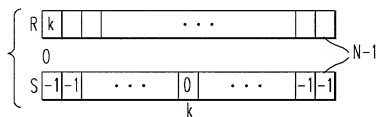


FIG. 22B

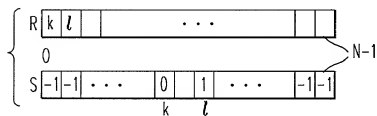
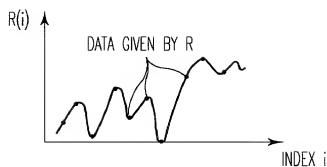


FIG. 22C





**FIG. 23**

$X \cdot Y \text{ MOD } 5$

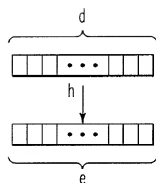
$X \backslash Y$	0	1	2	3	4
0	0	0	0	0	0
1	0	1	2	3	4
2	0	2	4	1	3
3	0	3	1	4	2
4	0	4	3	2	1

**FIG. 24A**

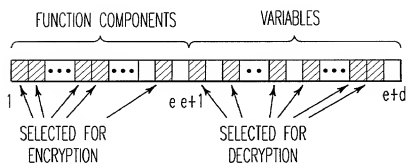
$X^Y \text{ MOD } 5$

$X \backslash Y$	0	1	2	3	4
0	1	0	0	0	0
1	1	1	1	1	1
2	1	2	4	3	1
3	1	3	4	2	1
4	1	4	1	4	1

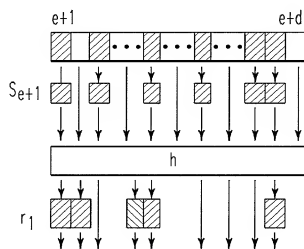
**FIG. 24B**



**FIG. 25A**



**FIG. 25B**



**FIG. 25C**

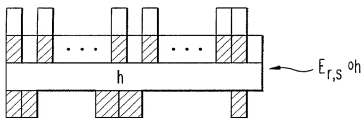


FIG. 26A

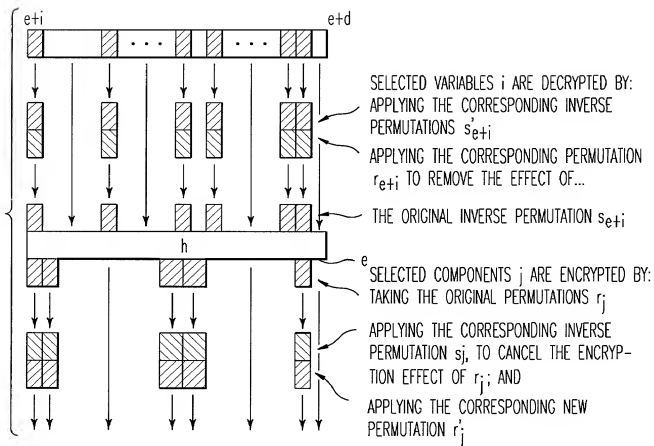


FIG. 26B

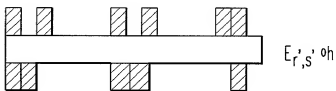


FIG. 26C

$x_2 \backslash x_1$	0	1	2	3	4
0	(3,4)	(1,2)	(4,0)	(2,1)	(1,3)
1	(0,0)	(2,3)	(3,4)	(4,1)	(0,2)
2	(2,0)	(3,2)	(1,2)	(0,1)	(1,4)
3	(4,0)	(2,0)	(4,4)	(4,4)	(2,4)
4	(1,1)	(2,2)	(1,0)	(4,1)	(4,2)

FIG. 27A

$x$	0	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
$t_f$	(2,3)	2	4	6	11	17	(1,3)	2	12	4	23	11	24	1	7	9	5	24	9	16	10	21	22	14

FIG. 27B

FUNCTION TABLE FOR  $f$ 

1	2	3	4	5
---	---	---	---	---

FUNCTION TABLE FOR  $t_f$ 

1	2	3	4	5
---	---	---	---	---

FIG. 27C

FIG. 27D

$x_1 \backslash x_2$	0	1	2	3	4
0	0	1	3	2	0
1	2	2	4	2	0
2	1	0	4	2	1
3	2	3	3	2	1
4	2	0	1	1	2

FIG. 28A

X	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
tf	23	0	2	4	6	11	17	13	2	12	4	23	11	24	1	7	9	5	24	9	16	10	21	22	14

FIG. 28B

X	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
tg	0	2	1	2	2	1	2	0	3	0	3	4	4	3	1	2	2	2	2	1	0	0	1	1	2

FIG. 28C

X	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
tg <sup>f</sup>	1	0	1	2	2	4	2	3	1	4	2	1	4	2	2	0	0	1	2	0	2	3	0	1	1

FIG. 28D

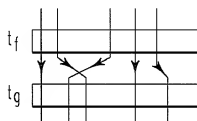


FIG. 28E

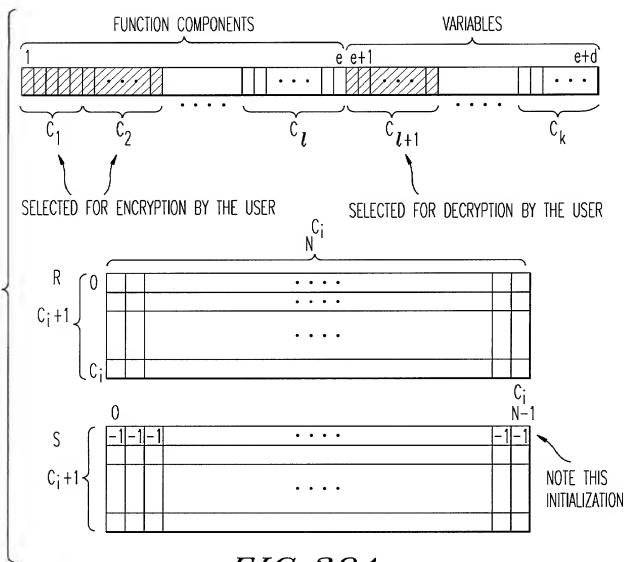


FIG. 29A

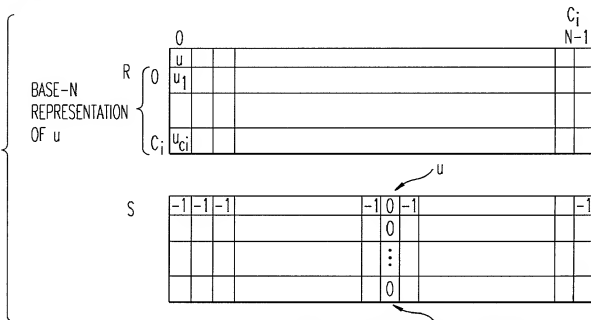
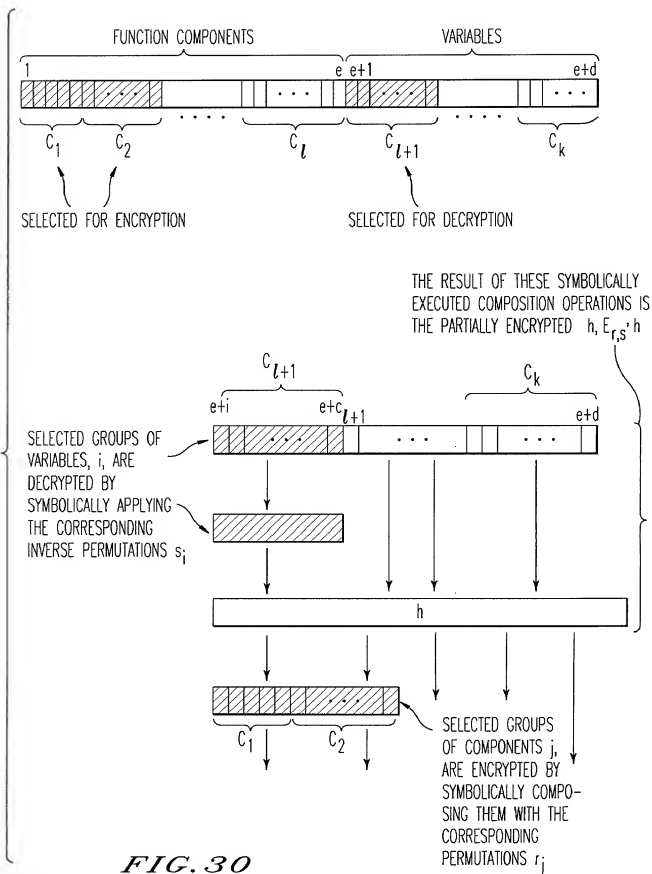


FIG. 29B



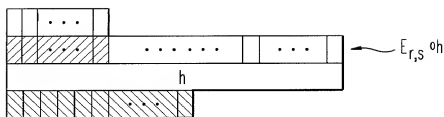


FIG. 31A C

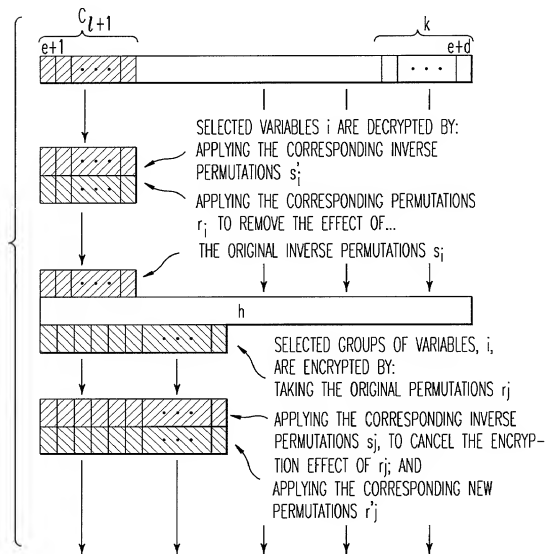


FIG. 31B

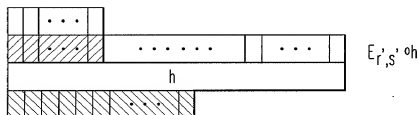


FIG. 31C



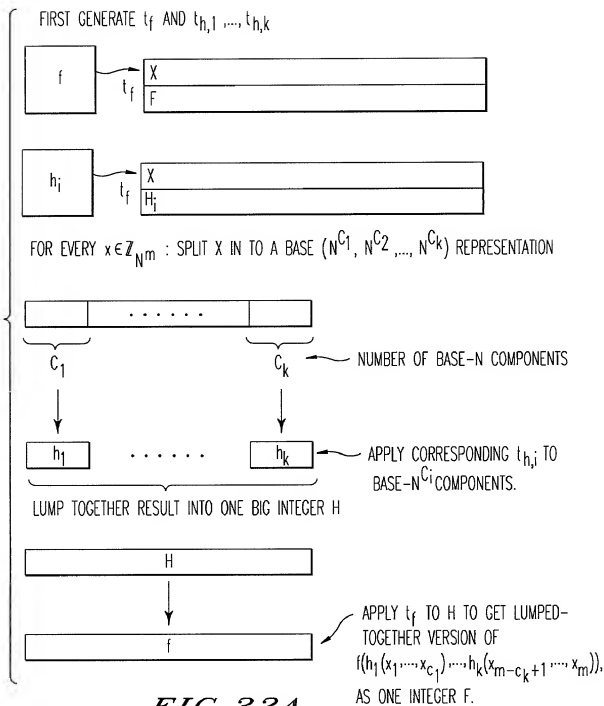


FIG. 32A

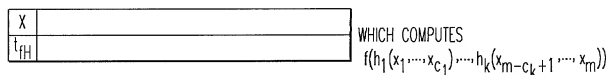


FIG. 32B

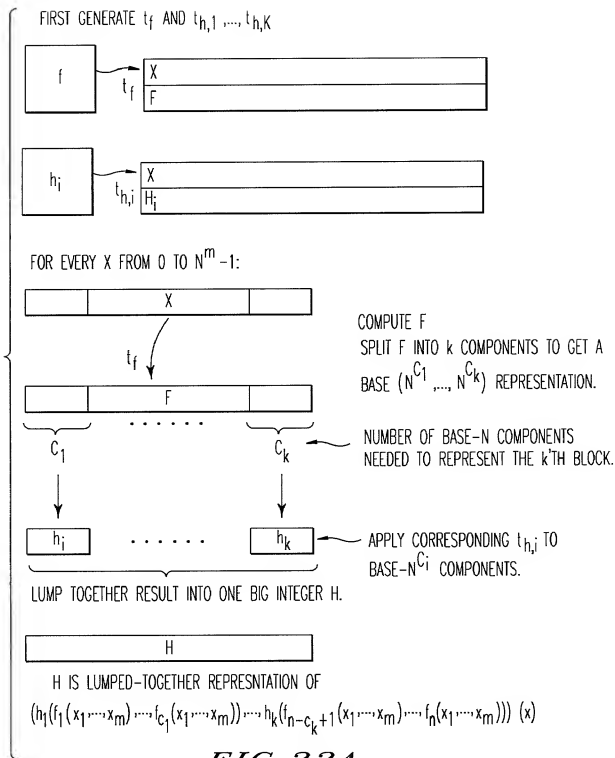
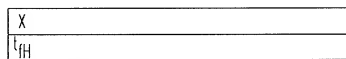


FIG. 33A



THAT COMPUTES  $(x)$ ,

FIG. 33B

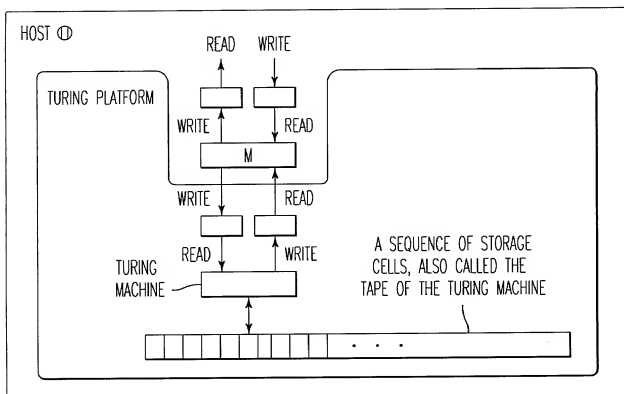


FIG. 34

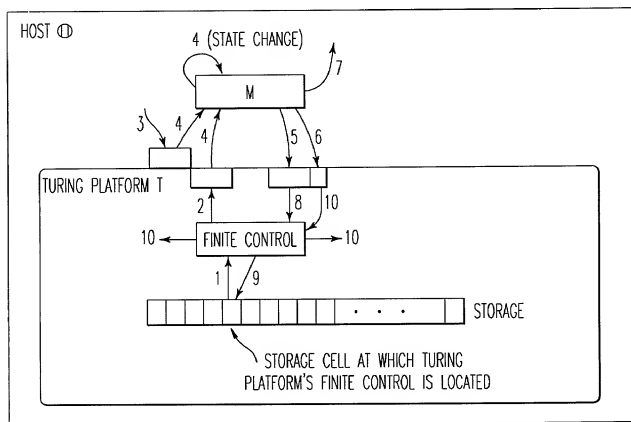


FIG. 35

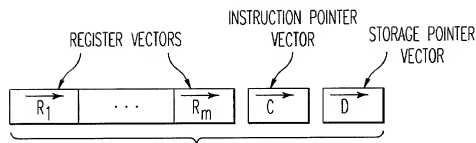


FIG. 36A

SHARED DATA IN THE  
FORM OF D-VECTORS

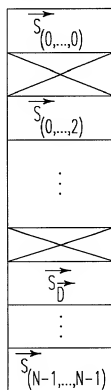


FIG. 36B

SET OF INSTRUCTIONS  
P

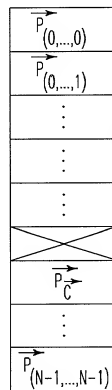


FIG. 36C

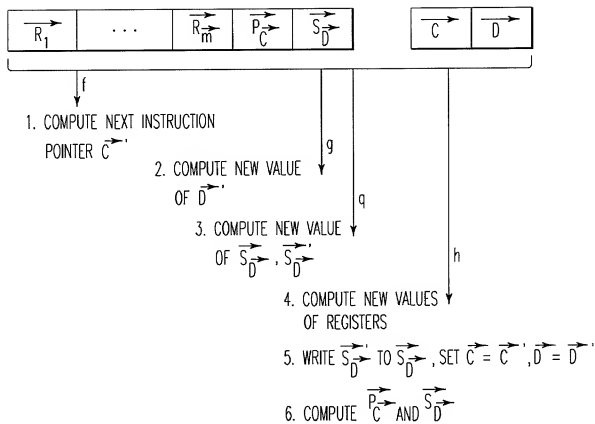


FIG. 36D

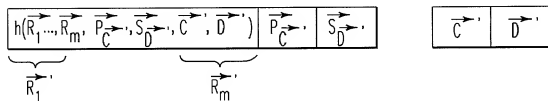
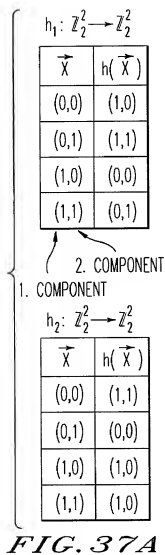


FIG. 36E



$f: \mathbb{Z}_2^4 \rightarrow \mathbb{Z}_2^3$

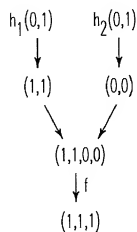
$\vec{x}$	$f(\vec{x})$
(0,0,0,0)	(1,0,1)
(0,0,0,1)	(0,0,1)
(0,0,1,0)	(1,0,1)
(0,0,1,1)	(0,0,0)
(0,1,0,0)	(1,0,0)
(0,1,0,1)	(0,0,0)
(0,1,1,0)	(1,1,1)
(0,1,1,1)	(1,0,0)
(1,0,0,0)	(1,1,0)
(1,0,0,1)	(0,0,1)
(1,0,1,0)	(0,1,1)
(1,0,1,1)	(1,0,1)
(1,1,0,0)	(1,1,1)
(1,1,0,1)	(0,0,0)
(1,1,1,0)	(1,1,0)
(1,1,1,1)	(0,1,0)

**FIG. 37B**

$g: \mathbb{Z}_2^3 \rightarrow \mathbb{Z}_2^3$

$\vec{x}$	$g(\vec{x})$
(0,0,0)	(1,0,1)
(0,0,1)	(0,0,0)
(0,1,0)	(1,1,1)
(0,1,1)	(1,0,0)
(1,0,0)	(0,1,1)
(1,0,1)	(1,0,1)
(1,1,0)	(1,1,0)
(1,1,1)	(1,1,1)

**FIG. 37C**



$$f: Z_2^4 \rightarrow Z_2^3$$

$\vec{x}$	$f(\vec{x})$
(0,0,0,0)	(1,0,1)
(0,0,0,1)	(0,0,1)
(0,0,1,0)	(1,0,1)
(0,0,1,1)	(0,0,0)
(0,1,0,0)	(1,0,0)
(0,1,0,1)	(0,0,0)
(0,1,1,0)	(1,1,1)
(0,1,1,1)	(1,0,0)
(1,0,0,0)	(1,1,0)
(1,0,0,1)	(0,0,1)
(1,0,1,0)	(0,1,1)
(1,0,1,1)	(1,0,1)
(1,1,0,0)	(1,1,1)
(1,1,0,1)	(0,0,0)
(1,1,1,0)	(1,1,0)
(1,1,1,1)	(0,1,0)

FIG. 38A

$$h_1: Z_2^2 \rightarrow Z_2^2$$

$\vec{x}$	$h_1(\vec{x})$
(0,0)	(1,0)
(0,1)	(1,1)
(1,0)	(0,0)
(1,1)	(0,1)

$$h_2: Z_2^2 \rightarrow Z_2^2$$

$\vec{x}$	$h_2(\vec{x})$
(0,0)	(1,1)
(0,1)	(0,0)
(1,0)	(1,0)
(1,1)	(1,0)

FIG. 38B

$$g: Z_2^4 \rightarrow Z_2^4$$

$\vec{x}$	$g(\vec{x})$
(0,0,0,0)	(0,0,0,0)
(0,0,0,1)	(1,1,0,0)
(0,0,1,0)	(0,1,0,0)
(0,0,1,1)	(1,0,1,1)
(0,1,0,0)	(0,0,1,0)
(0,1,0,1)	(1,0,1,1)
(0,1,1,0)	(0,1,1,0)
(0,1,1,1)	(0,0,1,1)
(1,0,0,0)	(0,0,1,0)
(1,0,0,1)	(1,1,0,0)
(1,0,1,0)	(1,1,1,0)
(1,0,1,1)	(0,1,0,0)
(1,1,0,0)	(0,1,1,0)
(1,1,0,1)	(1,0,1,1)
(1,1,1,0)	(0,0,1,0)
(1,1,1,1)	(1,0,1,0)

FIG. 38C

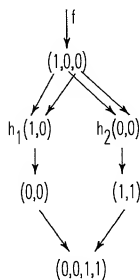


FIG. 38D

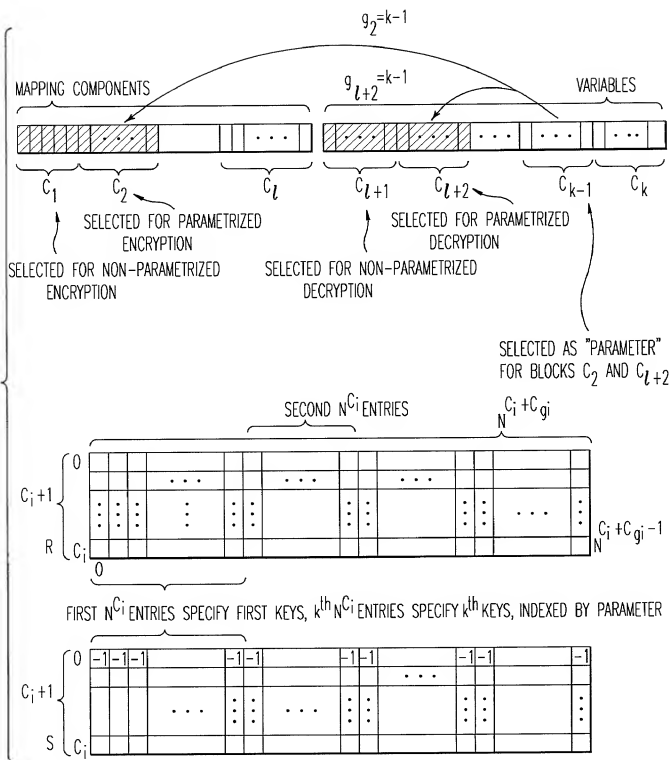


FIG. 39A



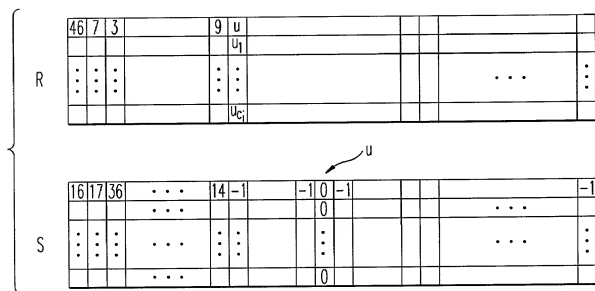
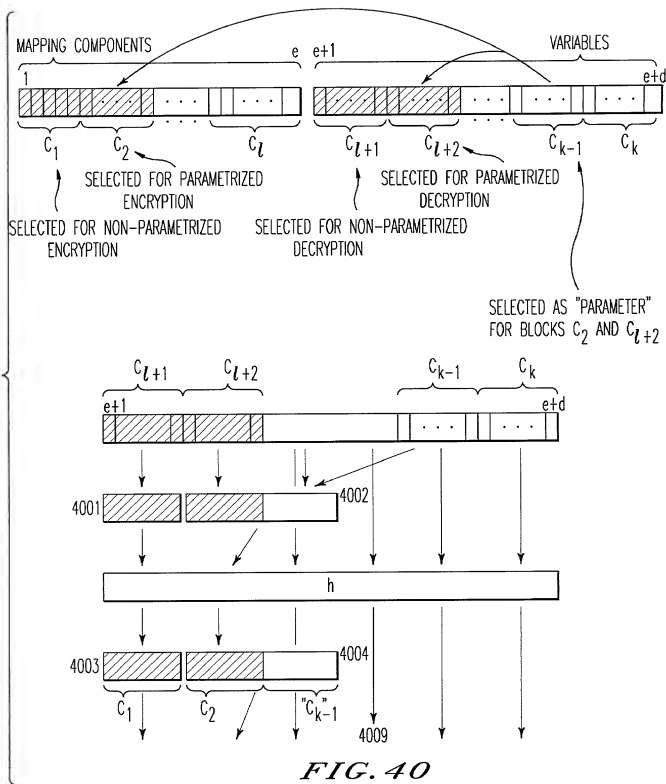


FIG. 39B



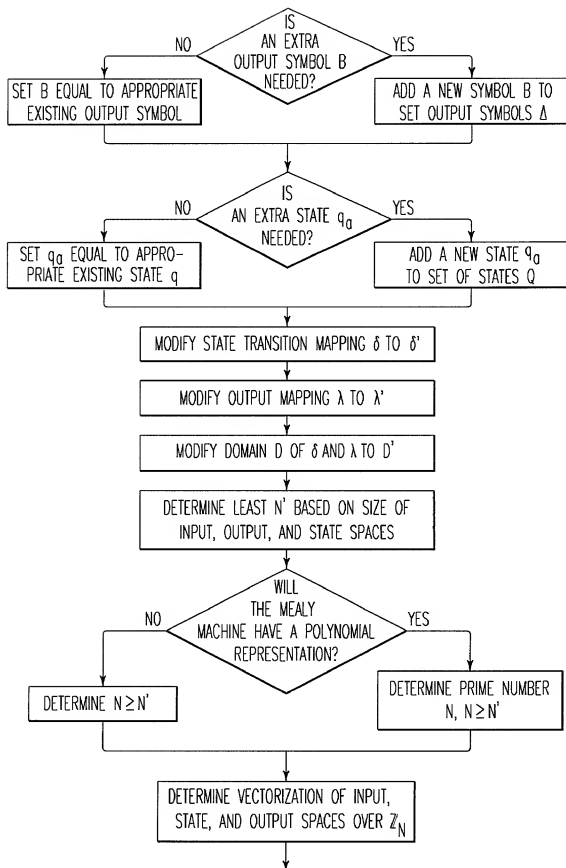


FIG. 41A

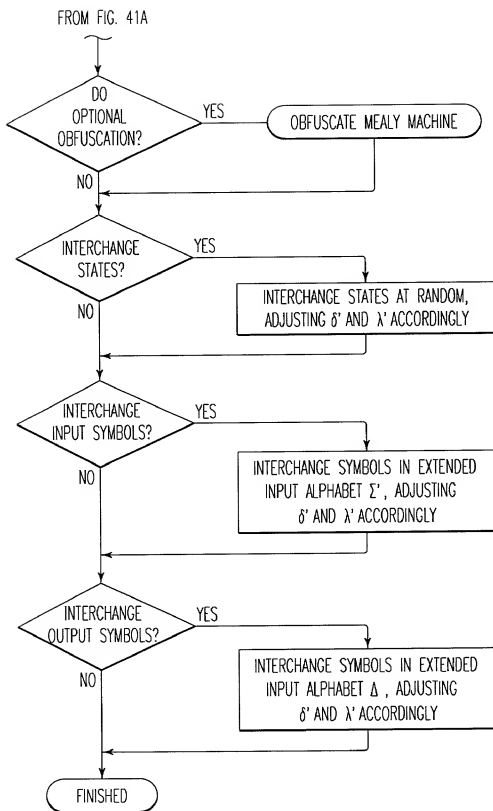


FIG. 41B

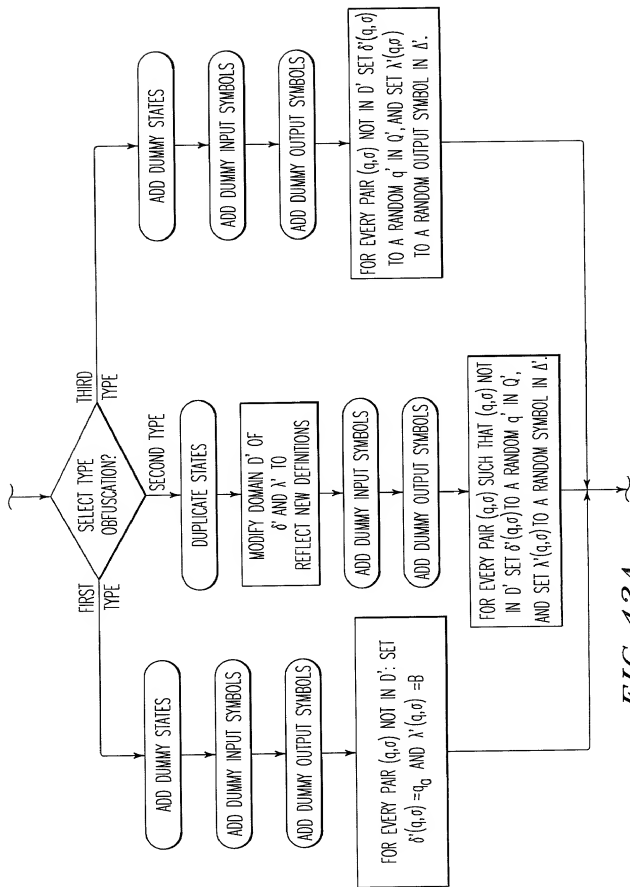


FIG. 42A

FIG. 42B

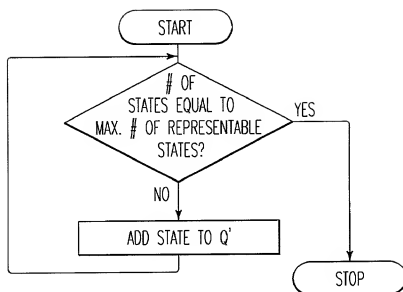


FIG. 42C

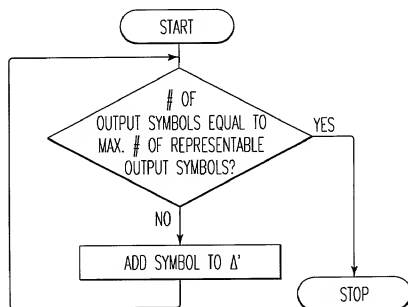
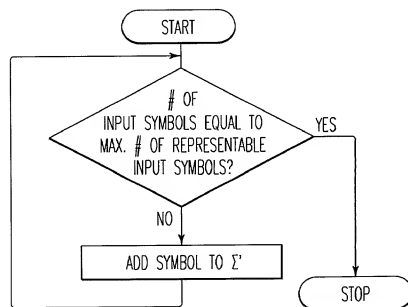


FIG. 42D



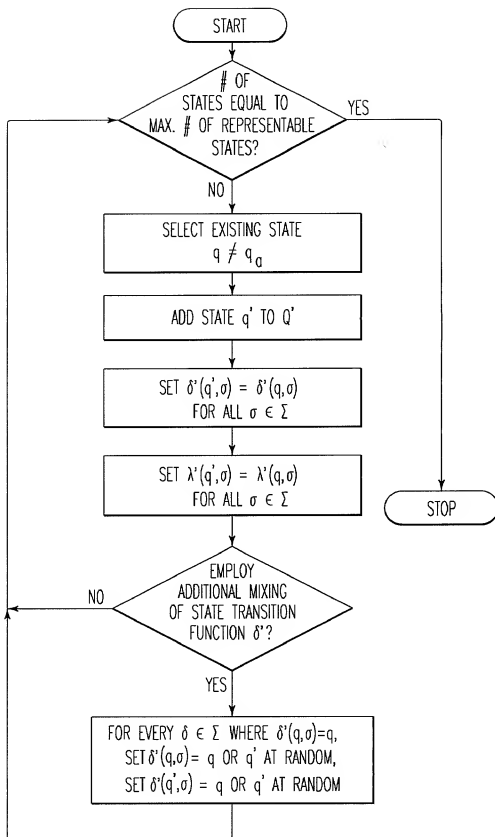
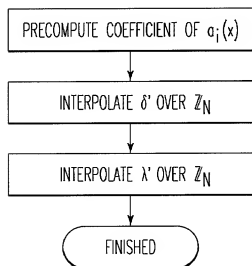
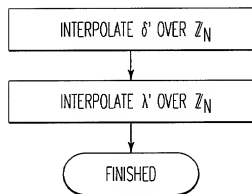


FIG. 42E

*FIG. 43A**FIG. 43B*



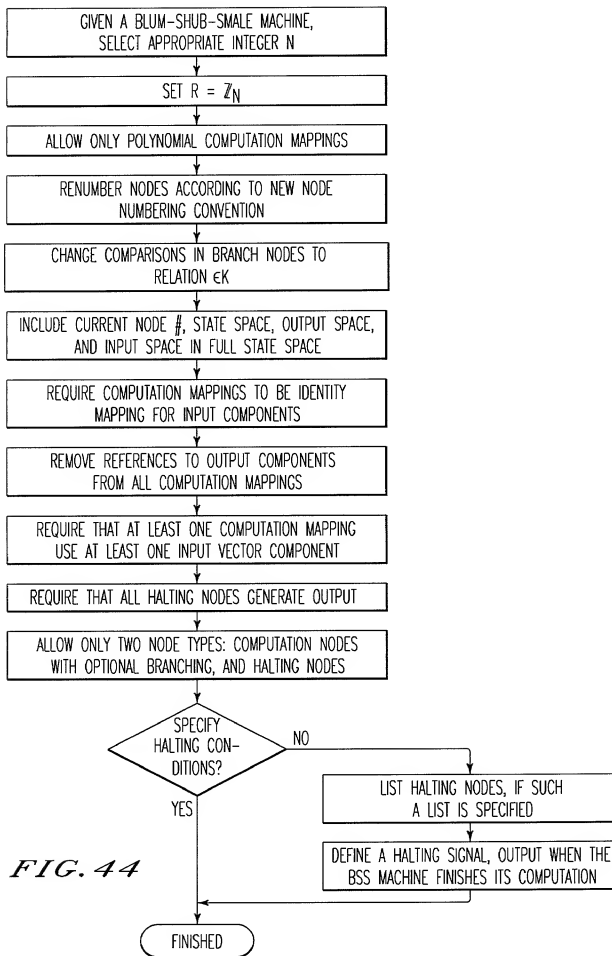
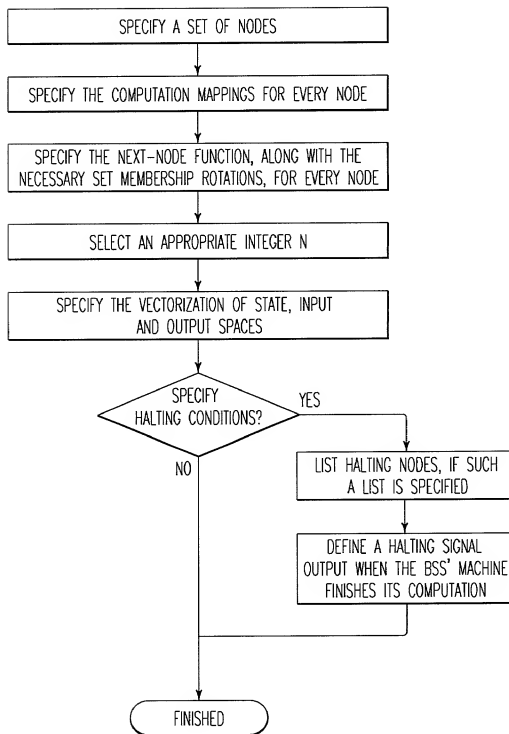
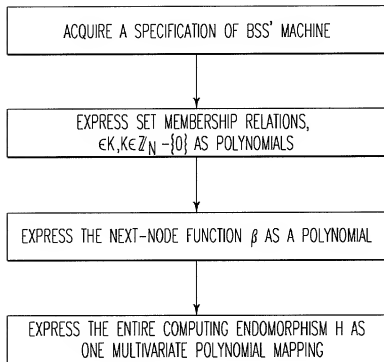


FIG. 44

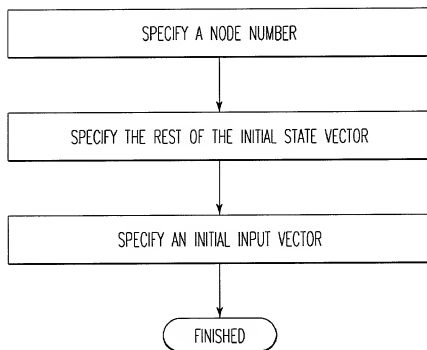
*FIG. 45*

*FIG. 46*

```

graph TD
    A{IS THE  
COMPUTING ENDOMORPHISM  
H GIVEN?} -- YES --> C[MULTIVARIATE POLYNOMIAL EXPRESSION FOR H]
    A -- NO --> B[ACQUIRE A SPECIFICATION OF THE BSS' MACHINE]
    B --> D[TRANSLATION SPECIFICATION INTO SINGLE  
MULTIVARIATE MAPPING]
    D --> C
    C --> E[INPUT OF H TO BASE  $N^{1+S+1}$  NUMBER X]
    E --> F[INVERT CORRESPONDING OUTPUT OF H TO  
BASE  $N^{1+S+0}$  NUMBER F]
    F --> G[INPUT F INTO  $x^{th}$  ENTRY IN FUNCTION TABLE]
    G --> H{HAVE ALL  
POSSIBLE INPUT COMBINATIONS  
FOR H BEEN  
TRIED?}
    H -- NO --> I[SELECT NEXT INPUT FOR H]
    I --> E
    H -- YES --> J[ ]
  
```

FIG. 47

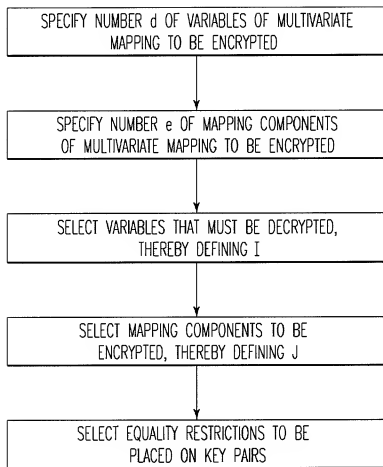
*FIG. 48*

```

graph TD
    A[INITIALIZE MACHINE WITH A SPECIFICATION FOR AN INITIAL STATE] --> B[DETERMINE HOW TO APPROPRIATELY EVALUATE H]
    B --> C[APPLY IT TO THE FULL STATE SPACE VECTOR]
    C --> D{READ OUTPUT?}
    D -- YES --> E[READ OUTPUT OF MACHINE]
    E --> D
    D -- NO --> F{CHANGE INPUT?}
    F -- YES --> G[CHANGE INPUT VECTOR]
    G --> F
    F -- NO --> H{HAS A HALTING CONDITION BEEN SATISFIED?}
    H -- YES --> I([FINISHED])
    H -- NO --> B

```

FINISHED

*FIG. 50*

```

graph TD
    A[DETERMINE APPROPRIATE REPRESENTATION FOR KEYS] --> B[ACQUIRE SPECIFIED PATTERN OF ENCRYPTION]
    B --> C[DETERMINE HOW MANY KEY PAIRS TO GENERATE FROM ENCRYPTION PATTERN]
    C --> D[PERMUTE  $Z_N$  WHILE RECORDING PERMUTATION DATA IN ARRAYS R AND S]
    D --> E{IS THE MAPPING TO BE ENCRYPTED REPRESENTED USING POLYNOMIALS?}
    E -- YES --> F[COMPUTE THE PERMUTATION AND ITS INVERSE BY INTERPOLATION, USING PRECOMPUTED  $a_i(x)$  AND ARITHMETIC TABLES IF SUCH IS COST EFFECTIVE]
    E -- NO --> G[STORE RESULT AS KEY DATA]
    F --> G
    G --> H{ARE ENOUGH KEY PAIRS GENERATED?}
    H -- YES --> I[ASSIGN EACH KEY PAIR  $i$  NOT GENERATED, BUT REQUIRED TO EQUAL PAIR  $j$ , TO THE SAME VALUE AS PAIR  $j$ ]
    H -- NO --> D
    I --> J[ EACH KEY PAIR MARKED AS AN IDENTITY MAPPING BY THE ENCRYPTION PATTERN IS SET TO THE IDENTITY MAPPING ]
    J --> K([FINISHED])
  
```

**FIG. 51**

FIG. 51



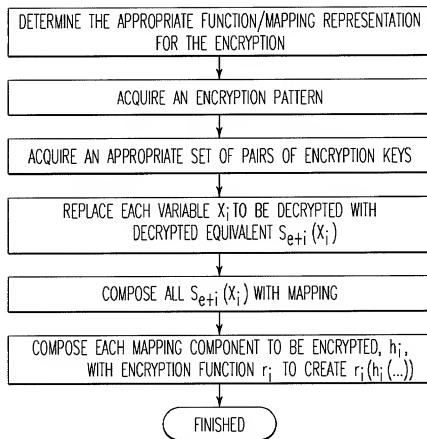


FIG. 52

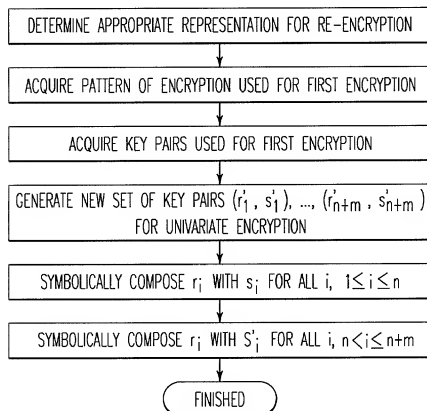


FIG. 53

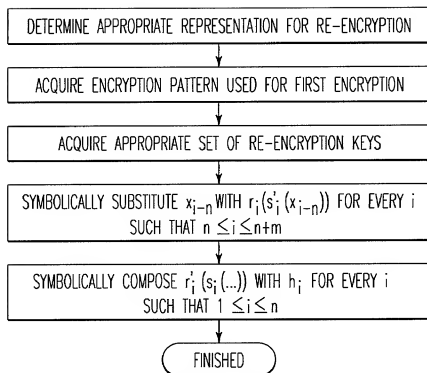


FIG. 54

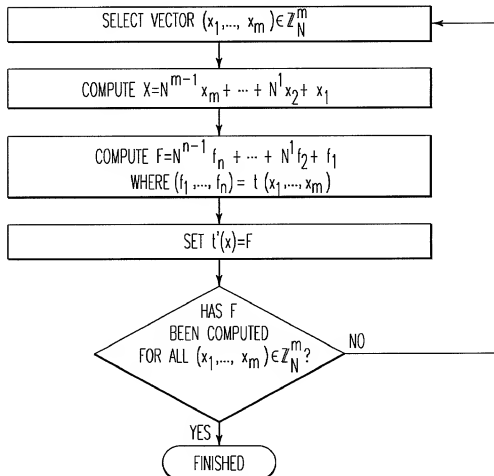


FIG. 55

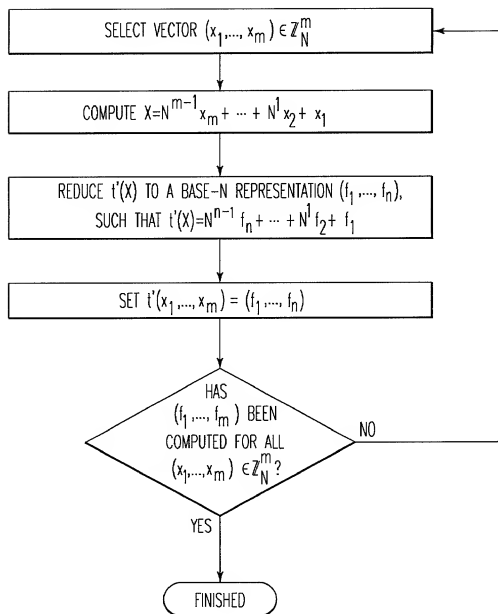


FIG. 56

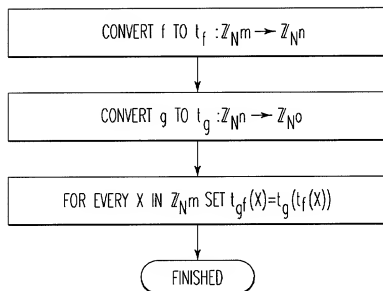


FIG. 57

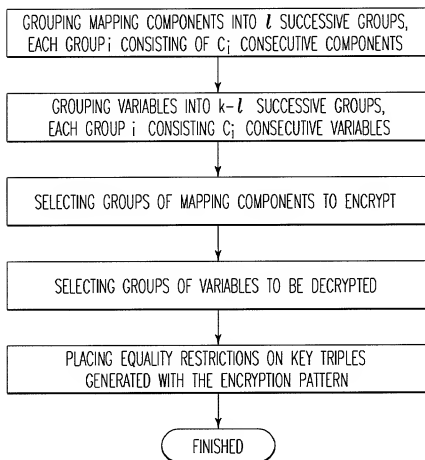


FIG. 58

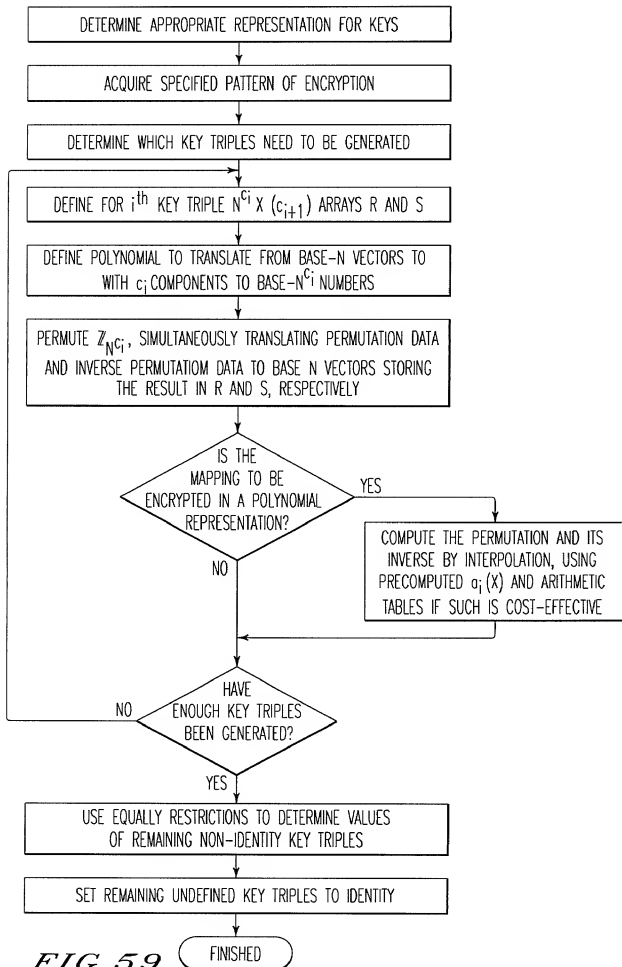


FIG. 59

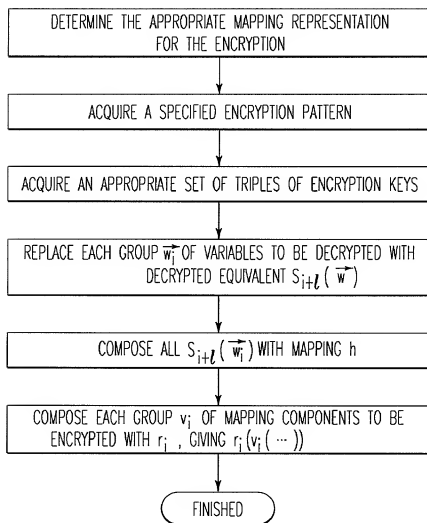


FIG. 60

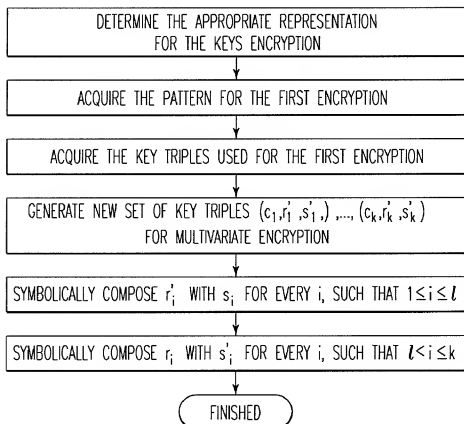


FIG. 61

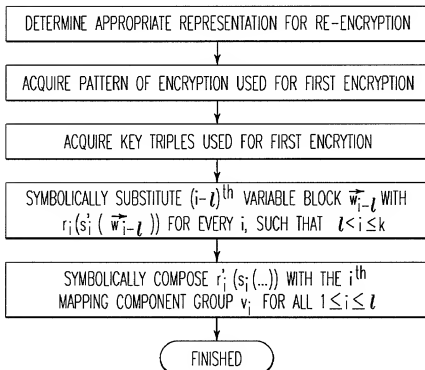


FIG. 62

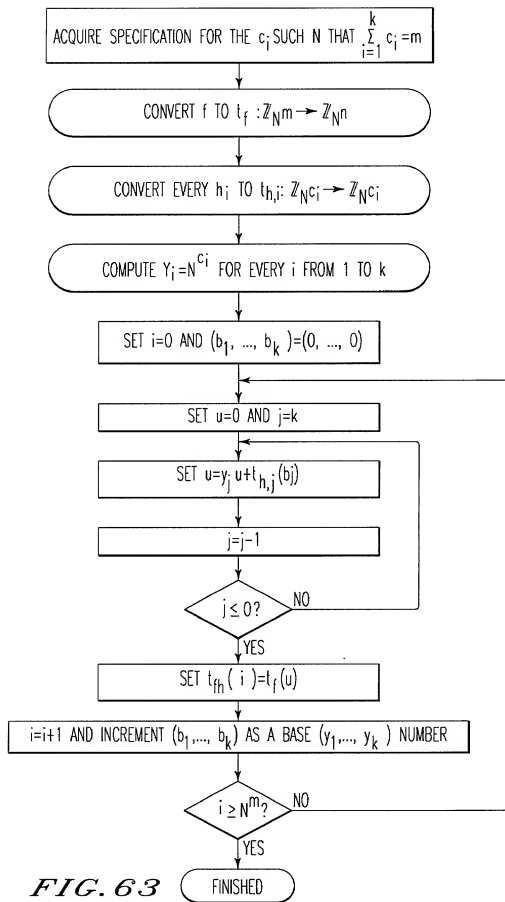


FIG. 63



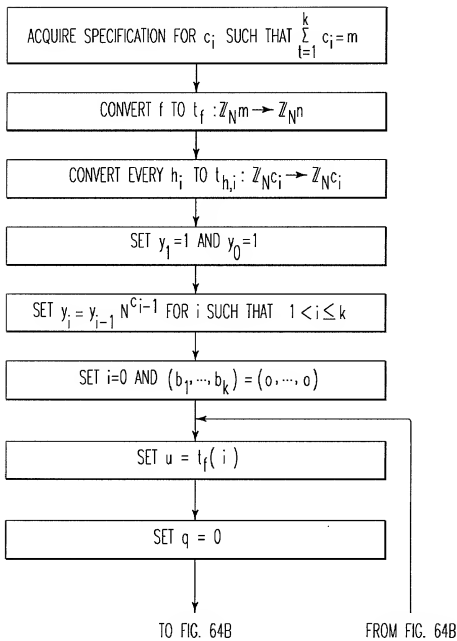


FIG. 64A

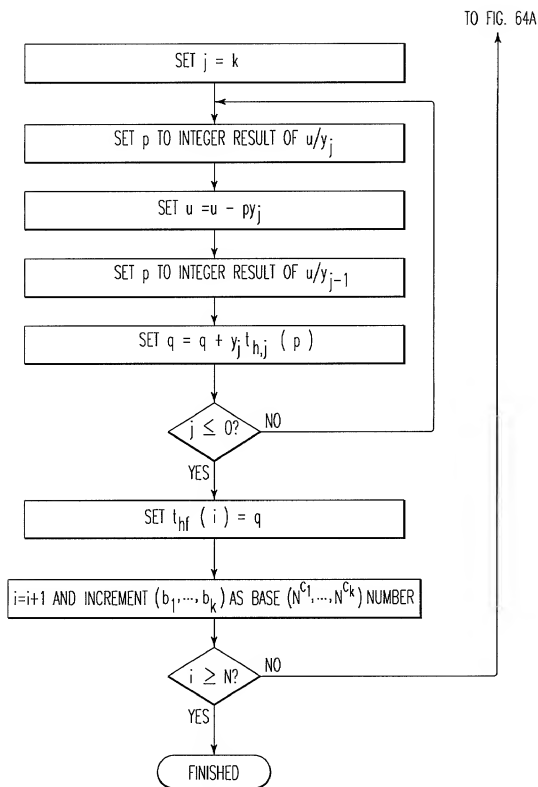


FIG. 64B

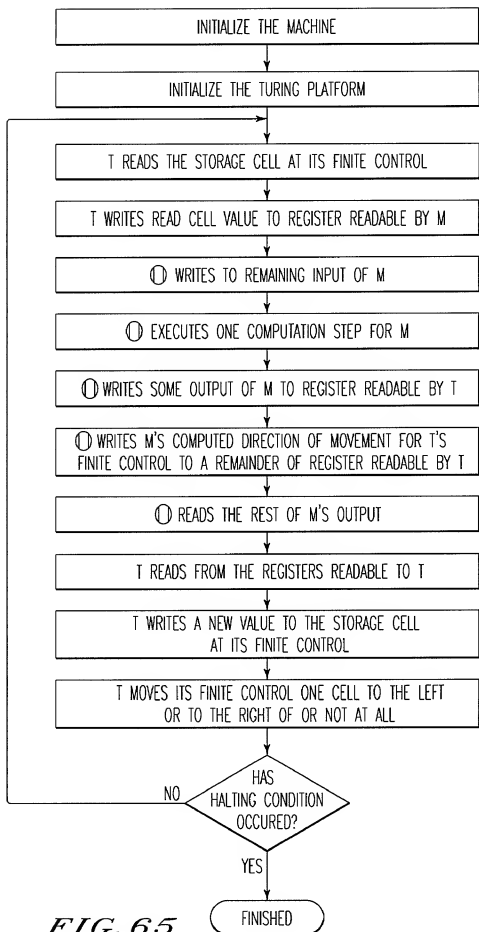


FIG. 65

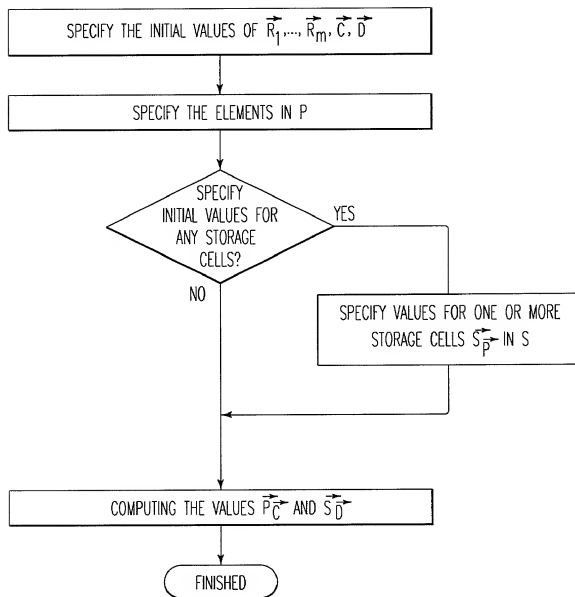


FIG. 66

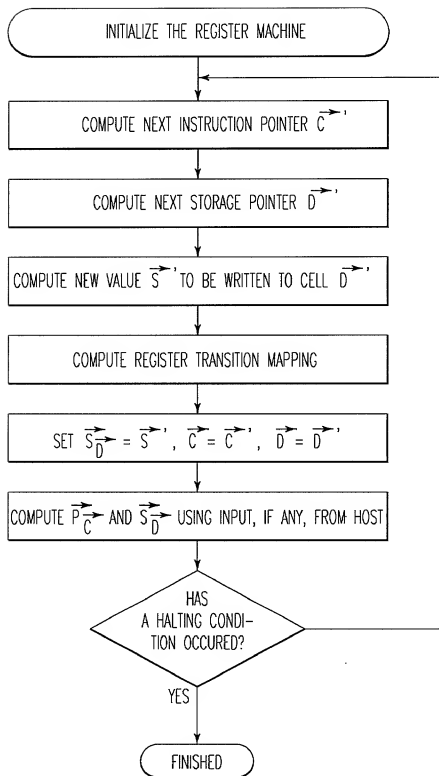


FIG. 67

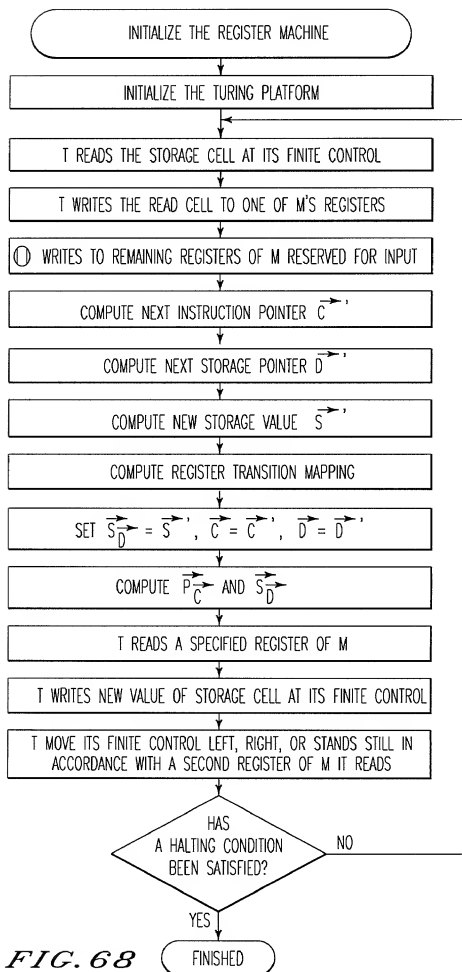


FIG. 68

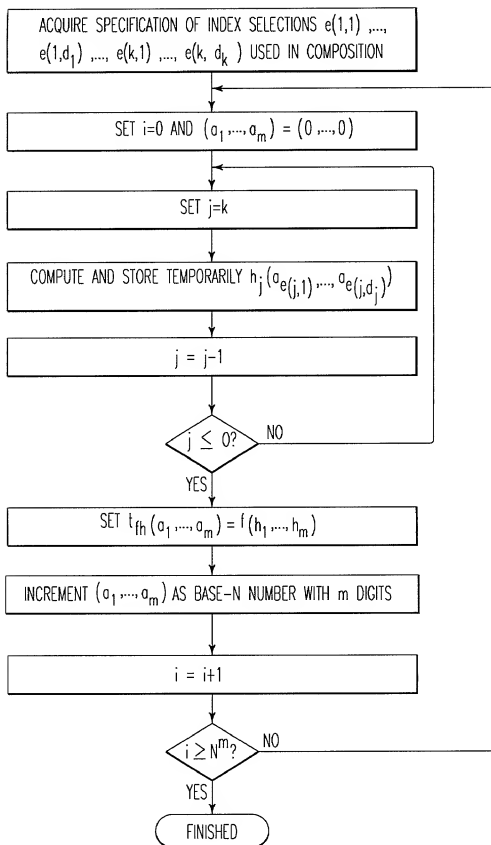


FIG. 69

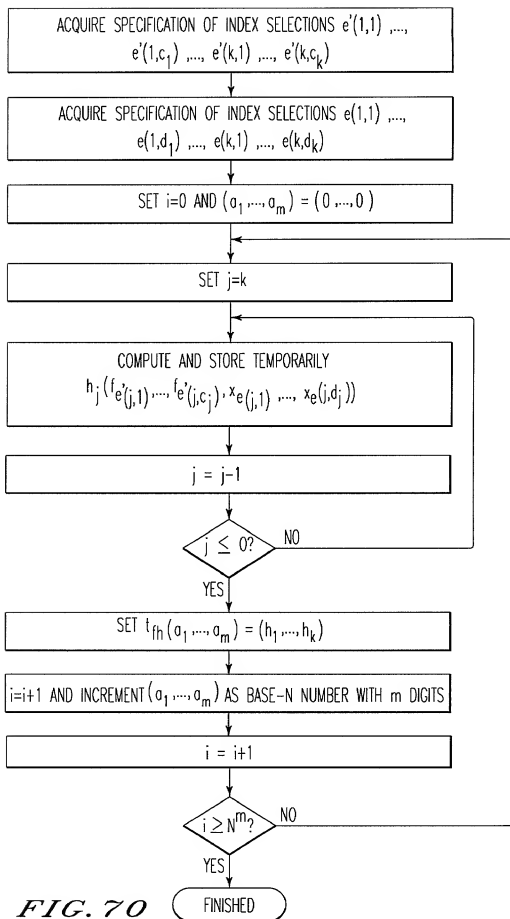


FIG. 70



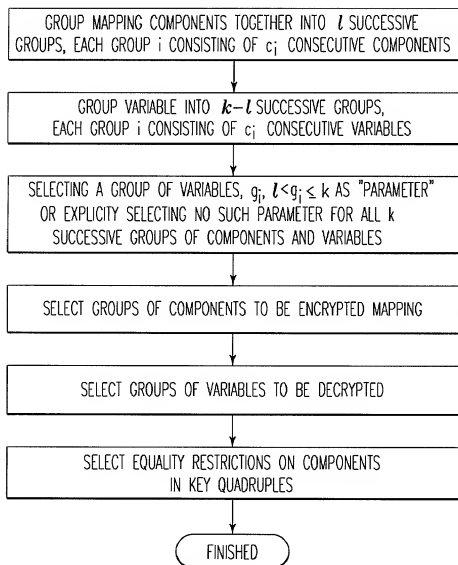


FIG. 71

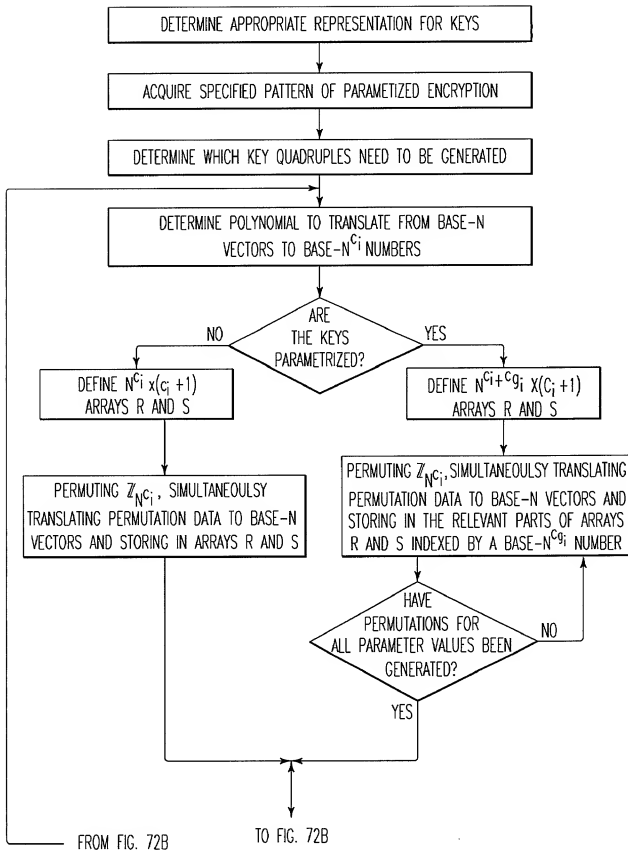


FIG. 72A

TO FIG. 72A

FROM FIG. 72A

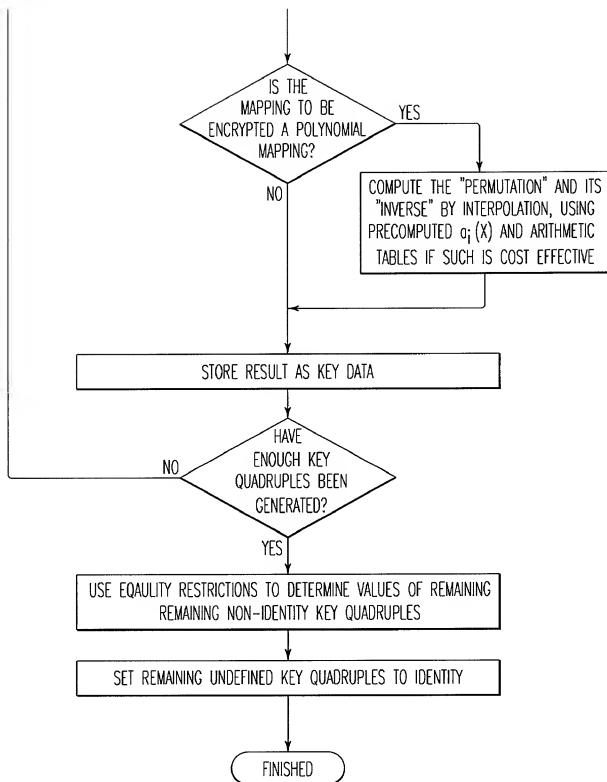


FIG. 72B

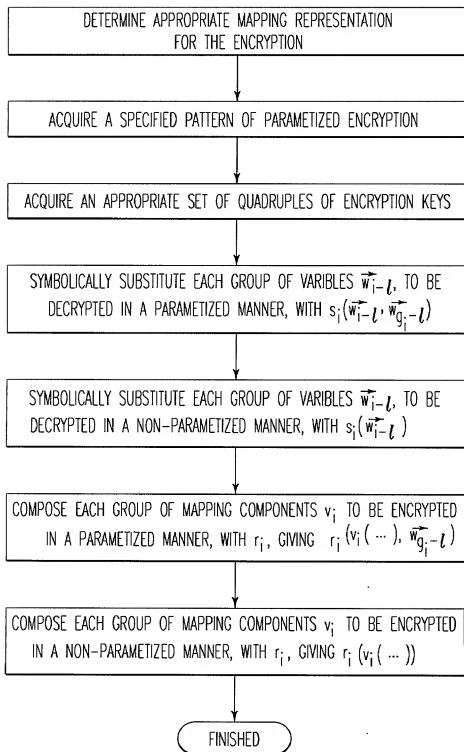
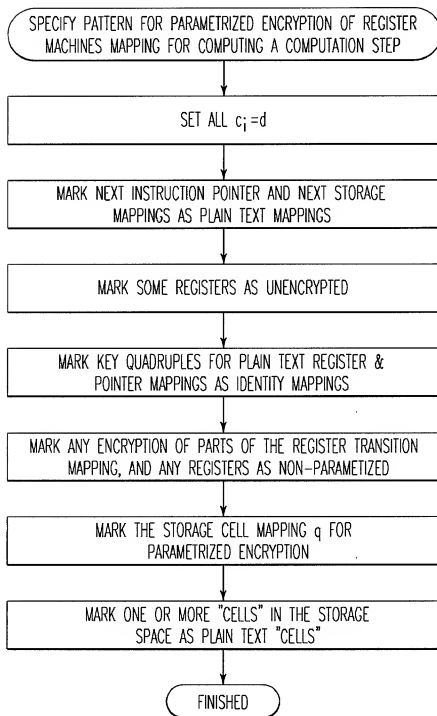


FIG. 73

*FIG. 74*

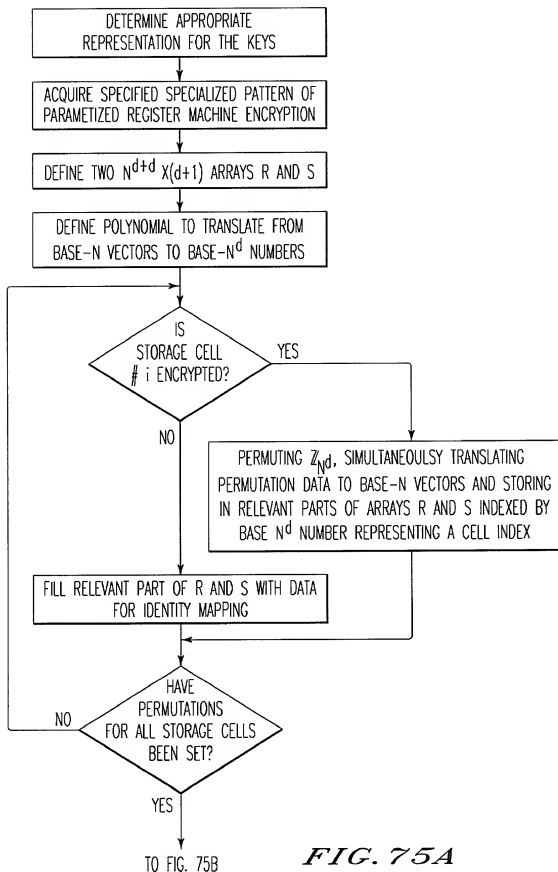


FIG. 75A

FROM FIG. 75A

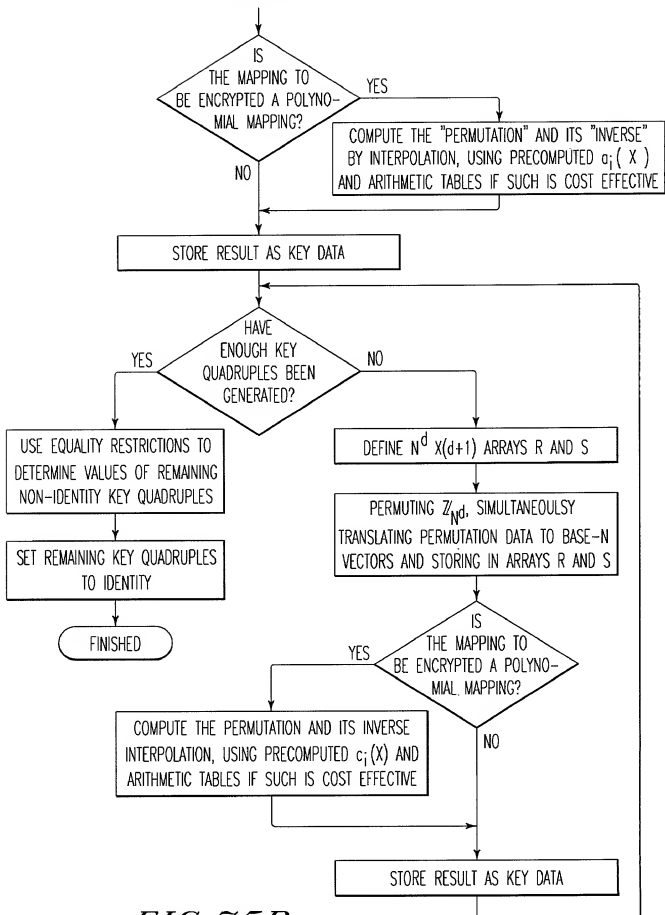
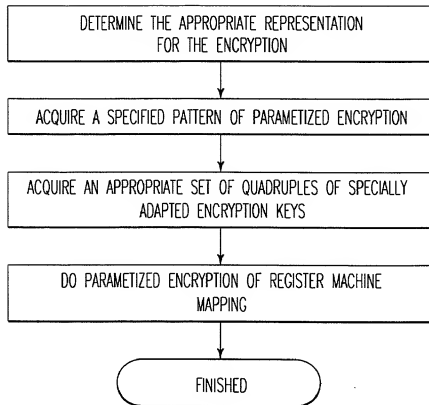


FIG. 75B

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*FIG. 76*